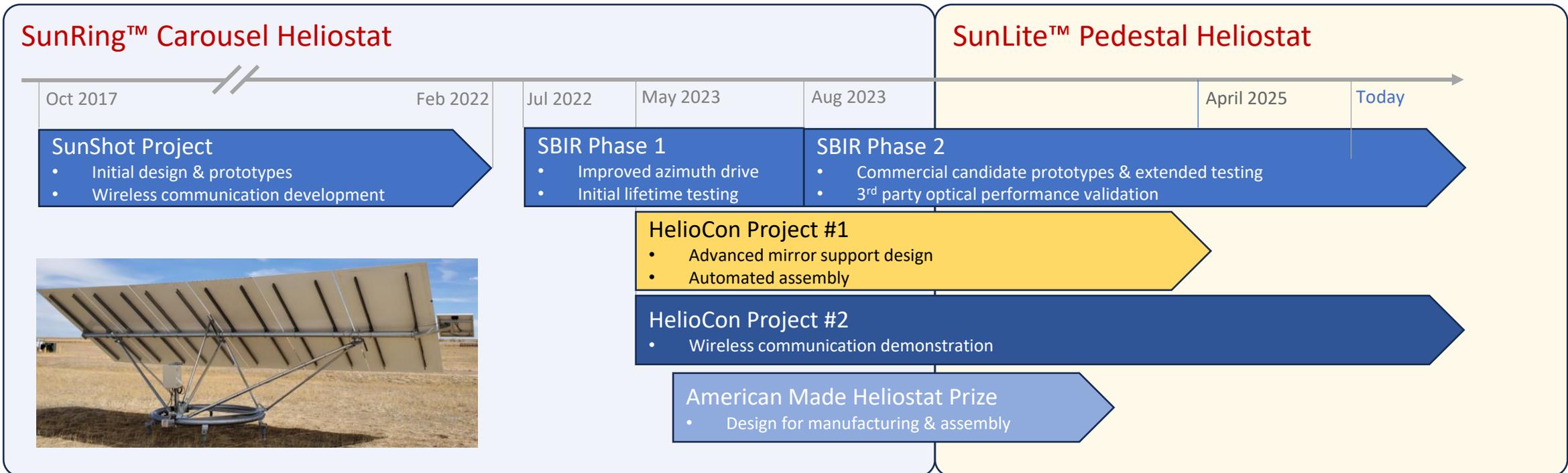


SunLite Heliostat: Mirror Array Optical Design, Tuning, And Testing

HelioCon Seminar July 23rd 2025

By: Kyle Kattke (presenter), Nathan Stegall, and Patrick Marcotte

- Solar Dynamics LLC - located in Denver, CO, USA
- Small company focused on CSP collector technology, TES, O&M services, & consulting
- Low-cost heliostat development since 2017
 - Focused on US market needs, supply chain, and manufacturing (but applicable worldwide)
 - Design suitable for large and small tower receivers
 - Supported by several US Dept. of Energy R&D and Heliostat Consortium (HelioCon) projects
 - Initial design focus on carousel heliostat, recent re-focus on pedestal heliostat with novel mirror support design



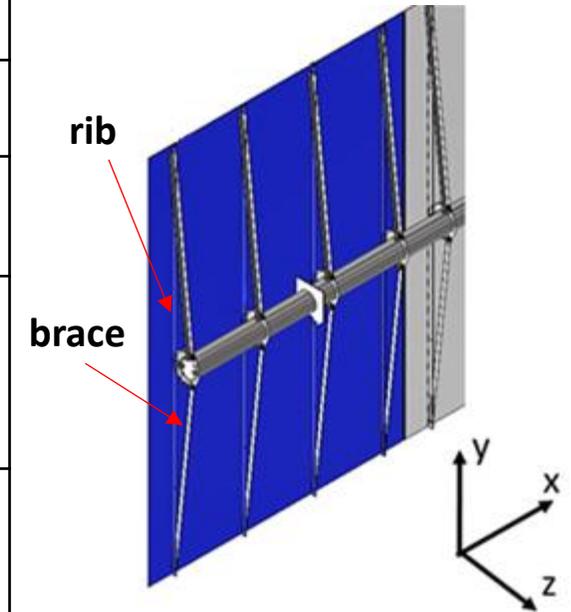


- Key design features
 - “Lite” streamlined design
 - Roll formed parts w/ minimal processing
 - Weld-free torque tube option
 - Mechanical clinches in place of bolts / rivets
 - Designed for automated assembly
- Advantages over SunRing
 - Faster time to market
 - Using off-the-shelf azimuth slewing drive vs. custom roller pinion based azimuth drive
 - 70% fewer parts, 83% fewer fasteners
 - Lower on-site labor & equipment costs
 - Greater % automated assembly

Mirror Area	21.2 m ²
Optical Shape	2-dimensional paraboloid
Mirror Array	3 facets in portrait
Power & Control	PV w/ battery wireless communication
Wind Criteria (3-sec gust)	18 m/s (40 mph) any orientation 47 m/s (105 mph) stow survival

SunLite Mirror Array Design Space

Design Parameter	Design Space	Down Selected Option(s)	Previous SunRing Design
Focusing	<ul style="list-style-type: none"> Flat, 1D, and 2D focusing 	2D paraboloid for overall mirror array	Flat
Mirror Size	<ul style="list-style-type: none"> Height: 3.21 m Width: 2.1-2.5 m 	3.21m x 2.2m	3.21 x 1.4m
Mirror Thickness	<ul style="list-style-type: none"> 3 mm 4 mm 	4mm	4mm
Facet Layout	<ul style="list-style-type: none"> 1 rows in portrait 2 rows in landscape 	1 row x 3 columns in portrait	1 row x 6 columns in portrait
Mirror Attachments	<ul style="list-style-type: none"> Ceramic pads Angle tabs Ribs Rib grid 	Bonded ribs	Bonded ribs
Mirror Bracing	<ul style="list-style-type: none"> None 2 braces per rib 4 braces per rib Shared between facets 	2 braces per rib & no-shared braces	None
Structural connections	<ul style="list-style-type: none"> Bolts and rivets Mechanical clinched 	Mechanical clinched	Bolts and rivets



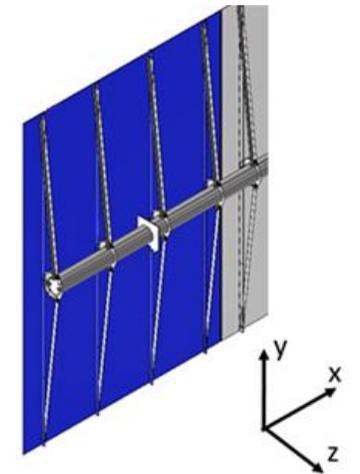
- Finite Element Analysis (FEA) model created to design mirror support structure
 - Survival wind load conditions to size members
 - Gravity load only conditions used to evaluate optical performance

Optical Performance Weighting Factors

Elevation Angle [°]	0-10	10-20	20-30	30-40	40-50	50-60	60-70	70-80	80-90
% of Annual Energy Delivered to Receiver	1%	11%	23%	23%	18%	11%	7%	4%	1%

- Minimizing gravity induced error through no-cost tuning
 - Elevation angle adjustment: compensate for overall rotation about x-axis
 - Achieved with correction factors as $f(\text{elevation angle})$ in heliostat's controller
 - Individual facet adjustment: compensate for local x- and y-axis errors
 - Achieved by tuning assembly jig for a *single elevation angle*
 - 30° is commercial target, used 90° for prototype

Mirror support structure



Slope Error as $f(\text{elevation angle})$ with Jig Tuned for 30° Elevation Angle

Elevation Angle [°]		15	30	45	60	75	Energy Weighted Average
RMS Slope Error [mrad]	SunLite – 75m FL	1.05	0.76	0.76	0.93	1.1	0.85

- Facets supported by 48 control points with vertical adjustability
 - Control points are adjacent to the 48 clinched connections between the mirror facets and mirror support structure
 - the mirror array is supported with similar boundary conditions on the workstation as on the heliostat
- **Optical Tuning Goal** – adjust height of control points such that these points when superimposed on mirror surface (mirror points) lie on the 2D paraboloid surface with a 75m focal length and compensate for gravity deformation at 90° elevation angle

Mirror array workstation – without facets

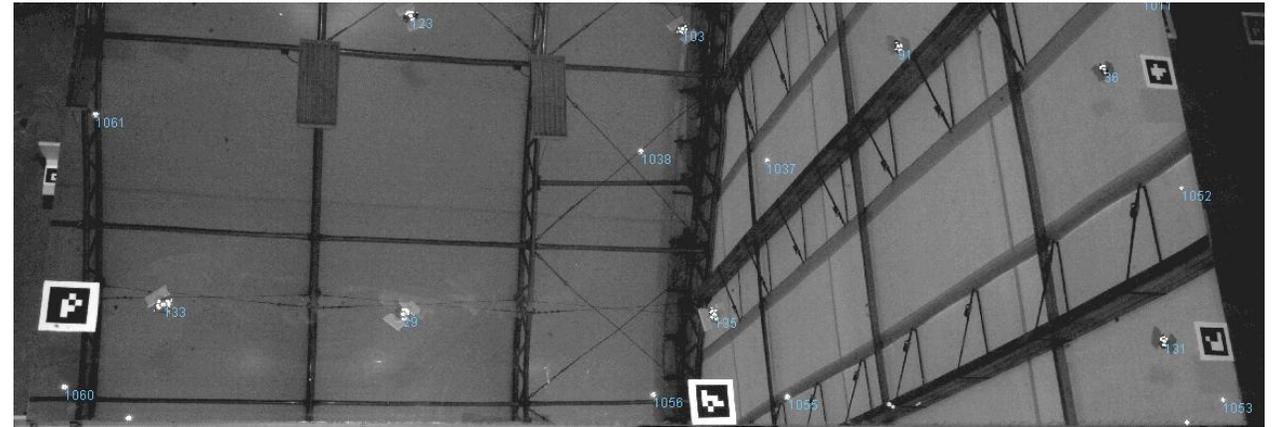


Mirror array workstation – with facets

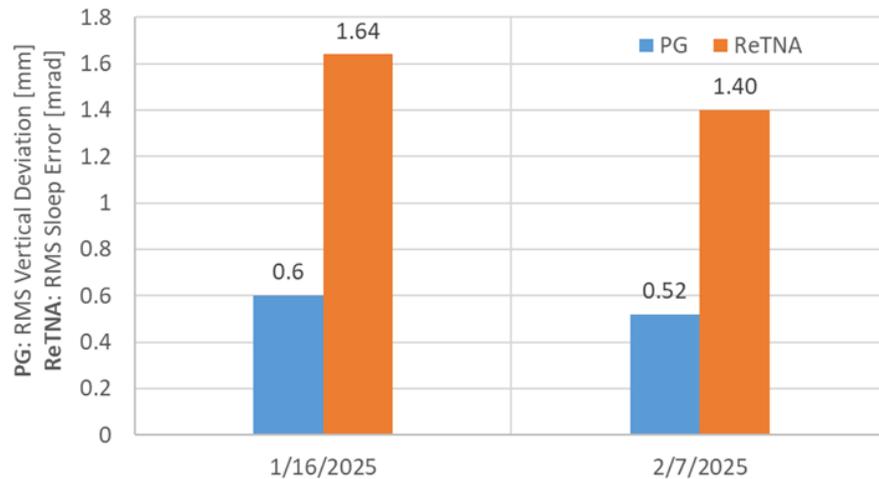


- Used Photogrammetry (PG) to measure the spatial position of the mirror points with mirror array lifted off jig and supported similar as when installed on the heliostat
 - Mirror points under gravity loading at 90° elevation angle
- Compared PG point cloud to ideal 75m FL paraboloid
 - Spatial difference became vertical corrections for each control point.
 - FEA showed that minimizing control point deviations also minimizes RMS slope error
 - Supported by ReTNA results

PG Identified Mirror Points on Portion of Mirror Array



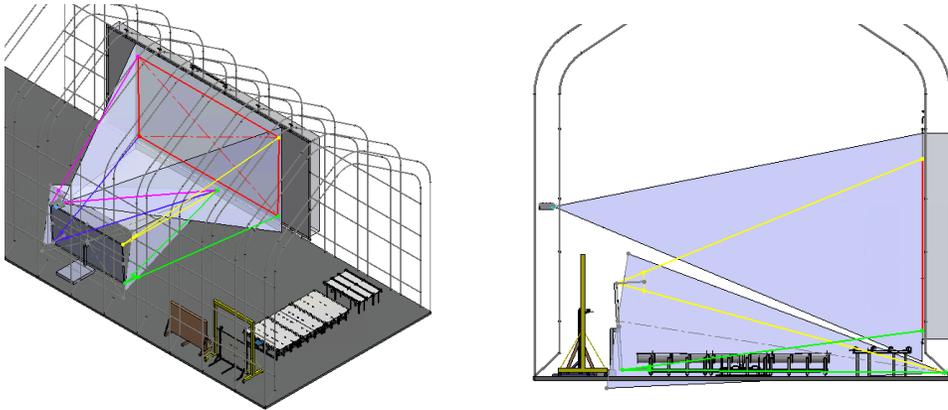
Error Progression in Final 2 Round of Jig Tuning



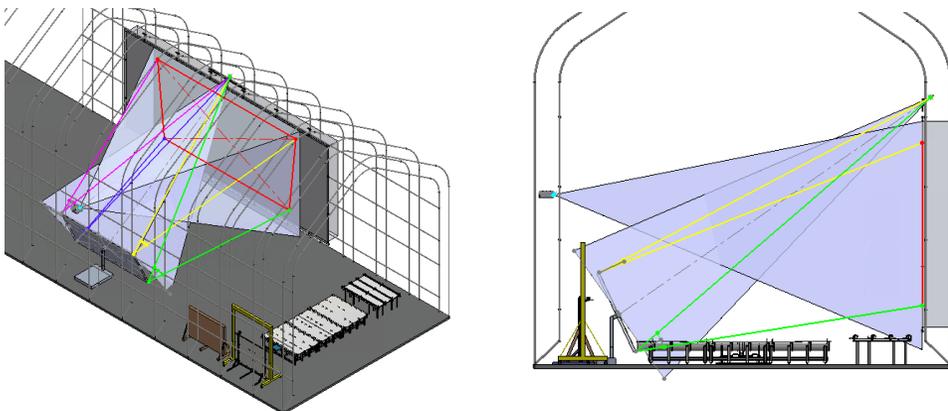
- Slope error would decrease further with subsequent jig tuning
 - FEA predicts an ideally tuned jig with actual prototype mirror facets yields 1.16 mrad RMS slope error
 - 21% higher than ideal FEA prediction with perfect mirror facets is within expectations
- Jig tuning stopped after 2/7 due to scheduling constraints, but will continue under SBIR project in Fall 2025

- Sandia designed SOFAST for SolarTAC test facility to:
 - Image complete mirror array
 - Capability of measuring at multiple elevation angles

Camera Position A: Measure at 3.5° Elevation

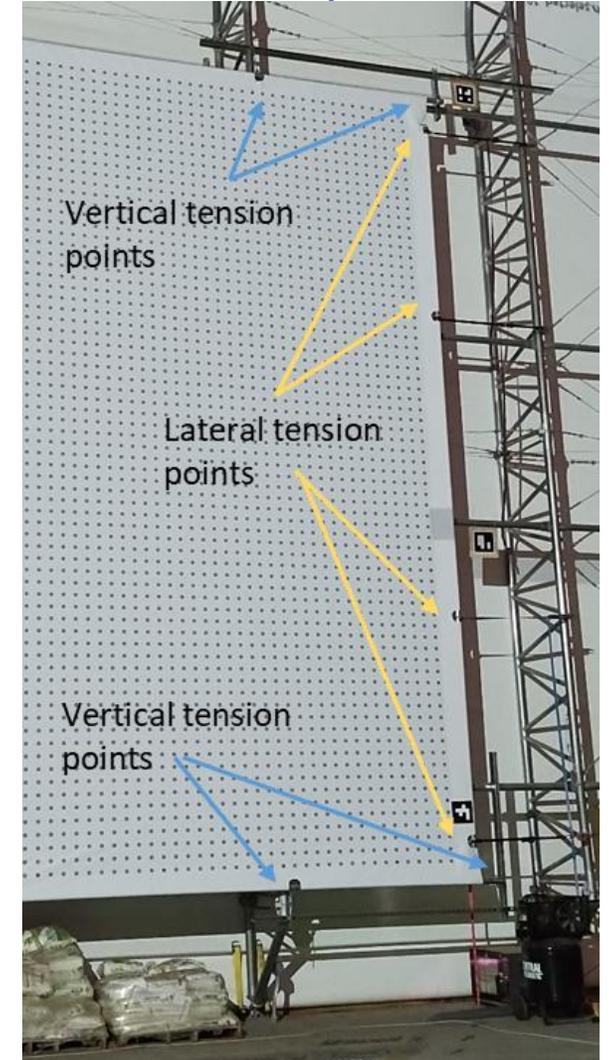


Camera Position B: Measure at 25° Elevation



- SD designed and deployed 1st of a kind stretched screen
 - 60.75 ft wide x 25 ft tall
 - Vinyl screen with pockets on 4 sides
 - Piping in pockets provide attachment points to pull tension
 - Testing limited to calm wind periods to minimize screen movement

Stretched Vinyl SOFAST Screen



- Sandia commissioned SOFAST at SolarTAC on in Oct 2024
 - Performed on 1st article mirror array (before optical tuning iterations)
 - Both SOFAST-fixed and SOFAST-fringe calibration and measurement photos taken
- Processed results from Sandia
 - Showed great agreement between SOFAST Fixed and Fringe

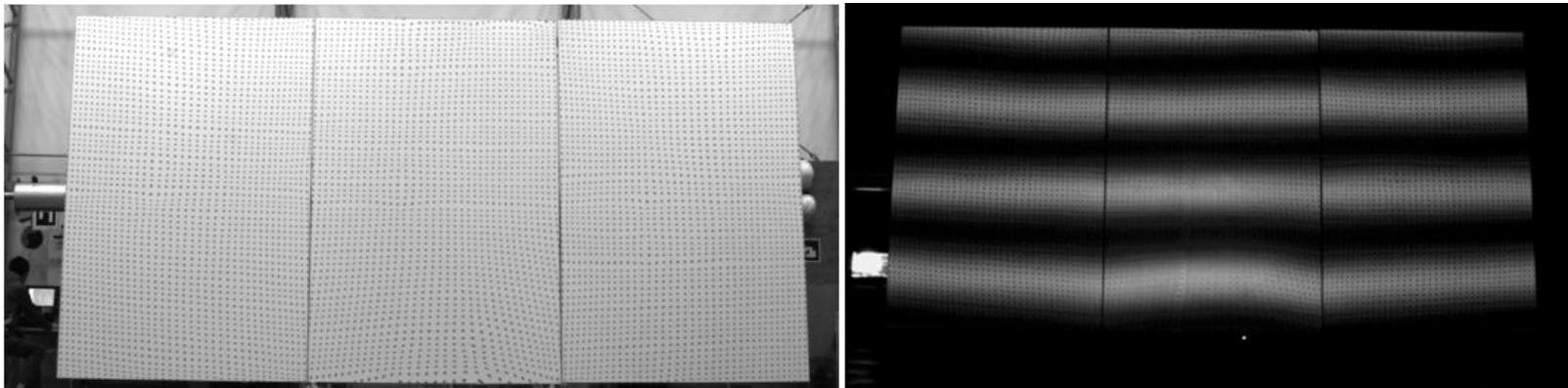
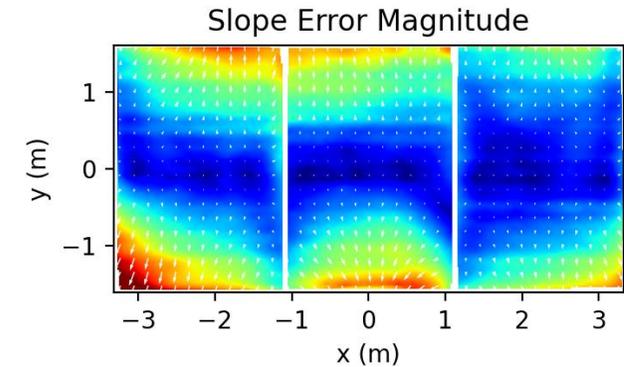


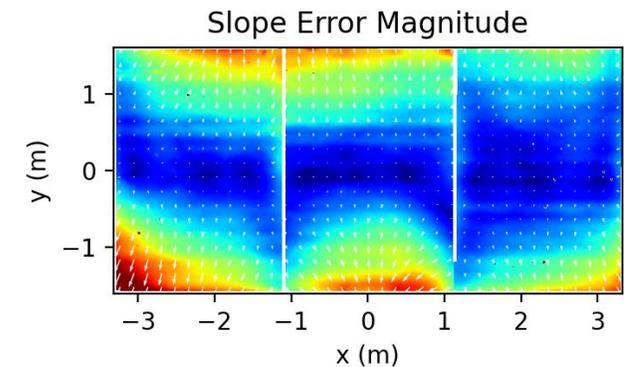
Image of mirror array at ~87° from SOFAST camera
Fixed mode (left) & fringe mode (right)

- Due to delay in SOFAST processing and difficulty moving mirror array on/off jig and onto cart, ReTNA was used as optical feedback for jig tuning

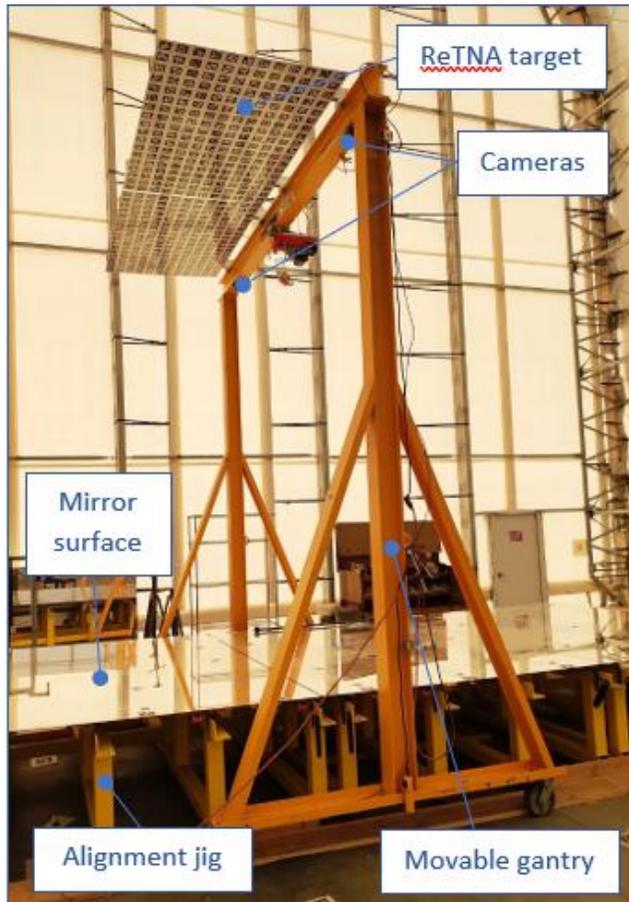
Fixed



Fringe



- ReTNA used to measure surface slope error with mirror array at 90° elevation angle
 - ReTNA target and cameras positioned above mirror array on gantry crane
 - Sequential pictures of target reflection gathered as gantry crane moved across mirror array
 - Images stitched together to represent the full mirror array



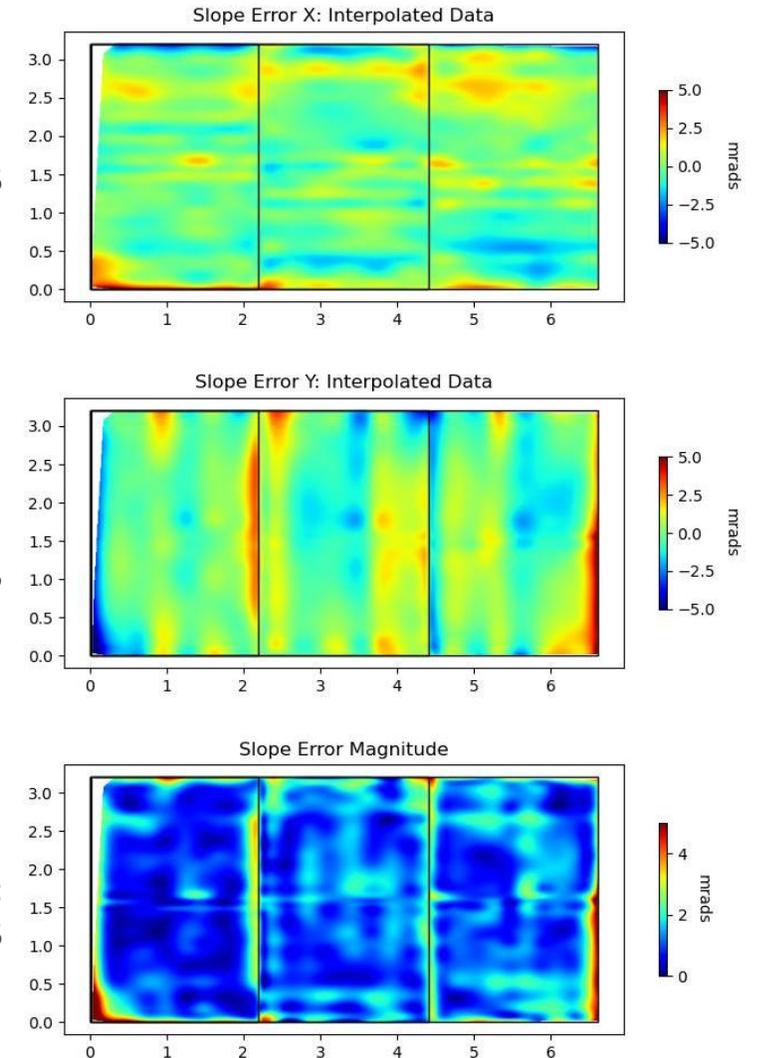
ReTNA Set-Up
During Measurement

Slope Error x-axis:
0.9 mrad RMS

Slope error y-axis:
1.1 mrad RMS

Slope error total:
1.4 mrad RMS

ReTNA Final Measurement

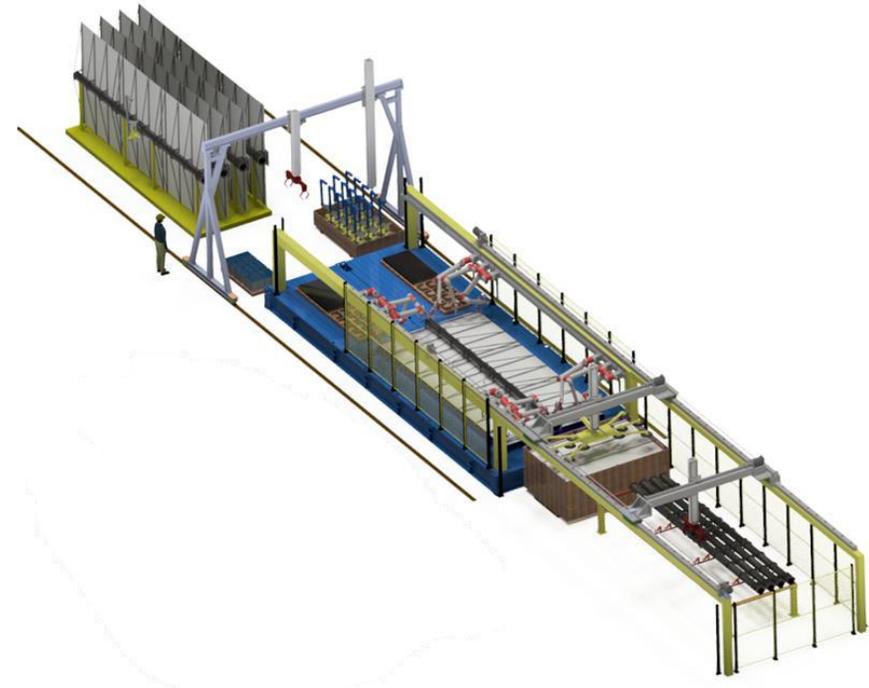


- Continue testing under SBIR funded project
 - Confirm tracking accuracy (0.5 mrad measured to date)
 - Perform additional optical tuning of mirror array jig to achieve commercial slope error performance
 - Jig tuned to commercial 30° elevation angle
 - Build up to 2 more SunLite's
- Prototype automated assembly system
 - Awaiting decision on DOE FOA proposal

1st SunLite Prototype – with mirror array from HelioCon project



Commercial Automated Assembly Line Design



Thank you!

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